



# **CY4632 Keyboard Firmware User's Guide**

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## CY4632 Keyboard Firmware User's Guide

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## **1. INTRODUCTION**

### **1.1 Scope**

The audience for this document is intended to be firmware developers that desire to understand and modify the firmware on the WirelessUSB LS Keyboard.

### **1.2 Overview**

This document will cover the design goals, architecture, firmware source code modules and configuration options for the WirelessUSB LS Keyboard. It will not cover the details of the radio subsystem or the configuration options that go with it. Please refer to the WirelessUSB Theory of Operation and CY4632 Protocol Library documents for theory of operation and details related to the radio subsystem.

### **1.3 Design Goals**

There are several design goals that drove the requirements for the firmware development for the keyboard. Some of these are architecture related, while others are feature related.

The CY4632 Reference Design Kit utilizes a PSoC controller for the RDK Keyboard (Cypress part #: CY8C27643-24PVXI). All references to PSoC in this document refer to the CY8C27643-24PVXI PSoC. Please contact your local sales representative for more information on this PSoC controller.

The architecture was designed to be modular for extendibility and maintainability. It was also designed so that it could easily be ported from one hardware platform to another assuming the use of a PSoC microprocessor. While porting to another microprocessor will require more work, the hardware design was done to minimize usage of advanced PSoC features to expedite this effort.

Design efforts have been made to reduce the on time of the microprocessor and radio to conserve battery life. This includes protocol optimizations along with using sleep features of the radio and PSoC microprocessor.

## 2. DEFINITIONS

Following are some definitions of acronyms and words found in this document. There may be other meanings to these definitions outside of this document.

**Bridge** – The Bridge is the receiving radio and USB hardware that connects to the PC and enumerates as a Human Interface Device.

**Device** – The reference to device in this document means the keyboard device that is sending packets via radio to the bridge.

**DVK** – A development kit produced by Cypress Semiconductor for showcasing Cypress products with a working development environment.

**HID** – Stands for Human Interface Device and is a product that allows an individual to interface with a computer. A keyboard and mouse are HID devices.

**PSoC** – A programmable mixed-signal array with an on-board processor.

**RDK** – A reference design kit produced by Cypress Semiconductor and used by 3<sup>rd</sup> parties to produce off-the-shelf products. Everything required to take a product to production is included in the kit. This document is part of the CY4632 Mouse/Keyboard RDK.

**USB** – The acronym for Universal Serial Bus, a well-known serial standard used in the computing world.

**WirelessUSB** – Trademark name for Cypress 2.4 GHz radio products.

### 3. HARDWARE OVERVIEW

#### 3.1 Schematic of PDC-9174 Board

The schematic of the RDK Keyboard (PDC-9174) can be found on the CY4632\_RDK release CD at:

\\Hardware\RDK Keyboard\LS RDK Keyboard Sch.pdf.

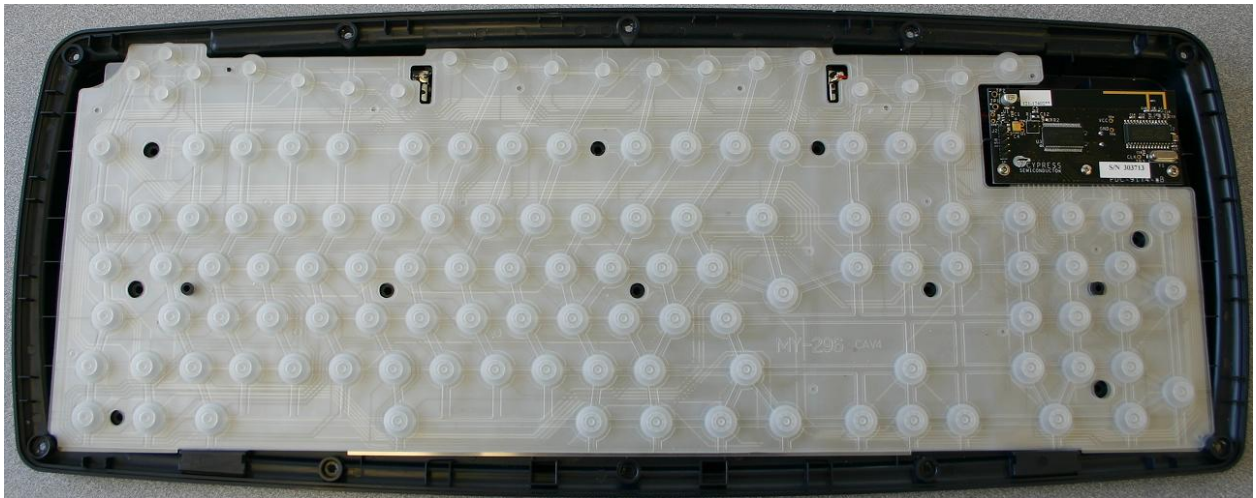
#### 3.2 RDK Keyboard Photographs



**Figure 1: Keyboard Plastic**

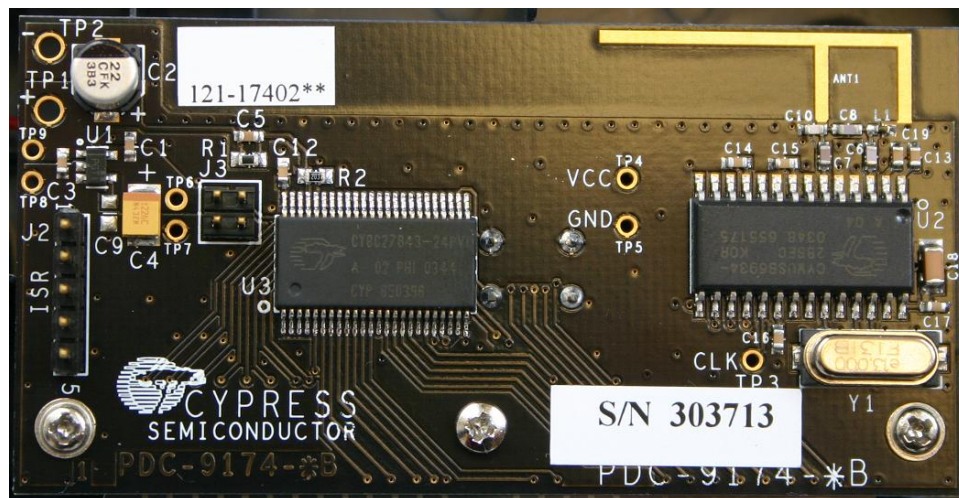
Figure 1 shows the RDK keyboard plastic.





**Figure 2: Exploded Keyboard**

Figure 2 shows the keyboard with the top removed. The radio/PSoC board (PDC-9174) is shown in the upper right hand corner.



**Figure 3: Radio & PSoC Board (PDC-9174)**

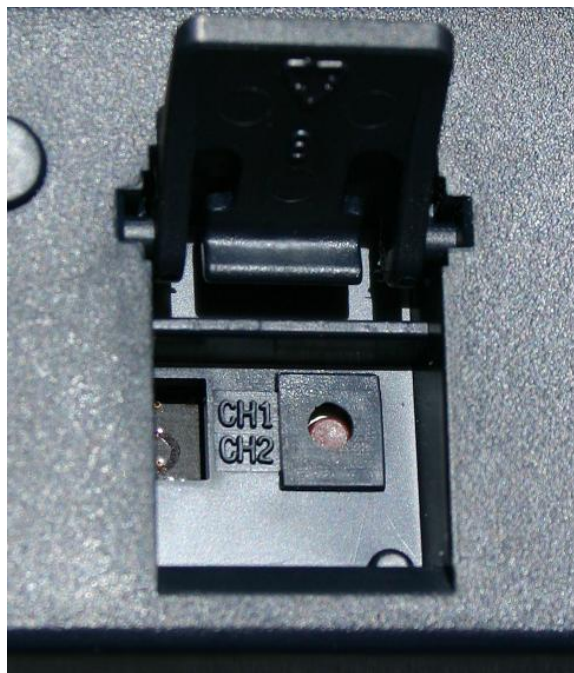
Figure 3 shows the main controller board with the PSoC and WirelessUSB LS Radio. The “F” trace is the antenna. All of the components are on the top side of the board with the exception of the bind button.





**Figure 4: Keyboard Battery Compartment**

Figure 4 shows the integrated battery compartment located on the bottom side of the keyboard. The battery compartment cover is also shown.



**Figure 5: Bind Button**

Figure 5 shows the bind button. The button access is located beneath the right adjustable foot on the bottom side of the keyboard.

### 3.3 Keyboard Matrix

The RDK keyboard matrix has 18 columns and 8 rows. Key presses generate a PSoC GPIO interrupt when a column is connected (shorted) to a row. The keyboard then scans the matrix to determine which keys have been pressed.

The RDK keyboard matrix with the USB scan codes are shown in Table 1.

**Table 1: RDK Keyboard Matrix**

	Row 1	Row 2	Row 3	Row 4	Row 5	Row 6	Row 7	Row 8
Column 1	0x14	0x17	0x1A	0x1C	0x08	0x18	0x15	0x0C
Column 2	0x5A	0x58	0x5B	0x44	0x62	0x45	0x63	0x46
Column 3	0x24	0x2D	0x25	0x2E	0x26	0x2A	0x27	0x2B
Column 4	0x60	0x5D	0x61	0x5E	0x56	0x57	0x5C	0x59
Column 5	NA	0x20	0x29	0x21	0x1E	0x22	0x1F	0x23
Column 6	0x3F	0x43	0x40	0x53	0x41	0x47	0x42	0x5F
Column 7	NA	0x00CD	NA	NA	0x0225	0x0226	NA	0x0227
Column 8	0x39	0x3B	0x2C	0x3C	0x4E	0x3D	0x3A	0x3E
Column 9	0x05	0x37	0x11	0x38	0x10	0x4C	0x36	0x55
Column 10	0x02	0x20	NA	0x00E2	0x0194	NA	0x00E9	0x65
Column 11	0x34	0x1D	0x35	0x1B	0x4D	0x06	NA	0x19
Column 12	NA	0x00B6	0x08	0x82	NA	NA	NA	NA
Column 13	0x07	0x0D	0x09	0x0E	0x0A	0x0F	0x0B	0x33
Column 14	NA	NA	0x83	NA	0x01	NA	0x10	0x54
Column 15	0x12	0x28	0x13	0x51	0x2F	0x04	0x30	0x16
Column 16	0x31	0x48	0x4A	0x50	0x52	0x4F	0x4B	0x49
Column 17	0x0223	0x0183	0x0224	0x00B7	NA	0x80	0x00B5	0x022A
Column 18	0x0192	0x0221	NA	0x04	0x00EA	0x40	0x18A	NA

**Notes:**

- Yellow indicates Multimedia Key (16-bit value)
- Red indicates Power Key
- Blue indicates Modifier Key
- No color indicates a Standard 101 Key

## **4. DEVELOPMENT ENVIRONMENT**

### **4.1 Tools**

The following tools are used to develop the RDK keyboard firmware and can be purchased from Cypress Semiconductor.

- PSoC Development Tools Solution
  - PSoC Designer Software version 4.1 SP1
  - PSoC ICE-4000
- ICCM8C C Compiler version 1.28
- Relevant PSoC POD Kit

A Microsoft Windows based PC is used for tool execution.

### **4.2 PSoC Configuration**

The PSoC is configured with one 8-bit timer module as a clock and an SPI module for radio communication. An optional UART module may be configured and used as a debug port. All other PSoC features were not utilized to maintain compatibility with other microprocessor implementations.

## 5. FIRMWARE ARCHITECTURE

### 5.1 Model

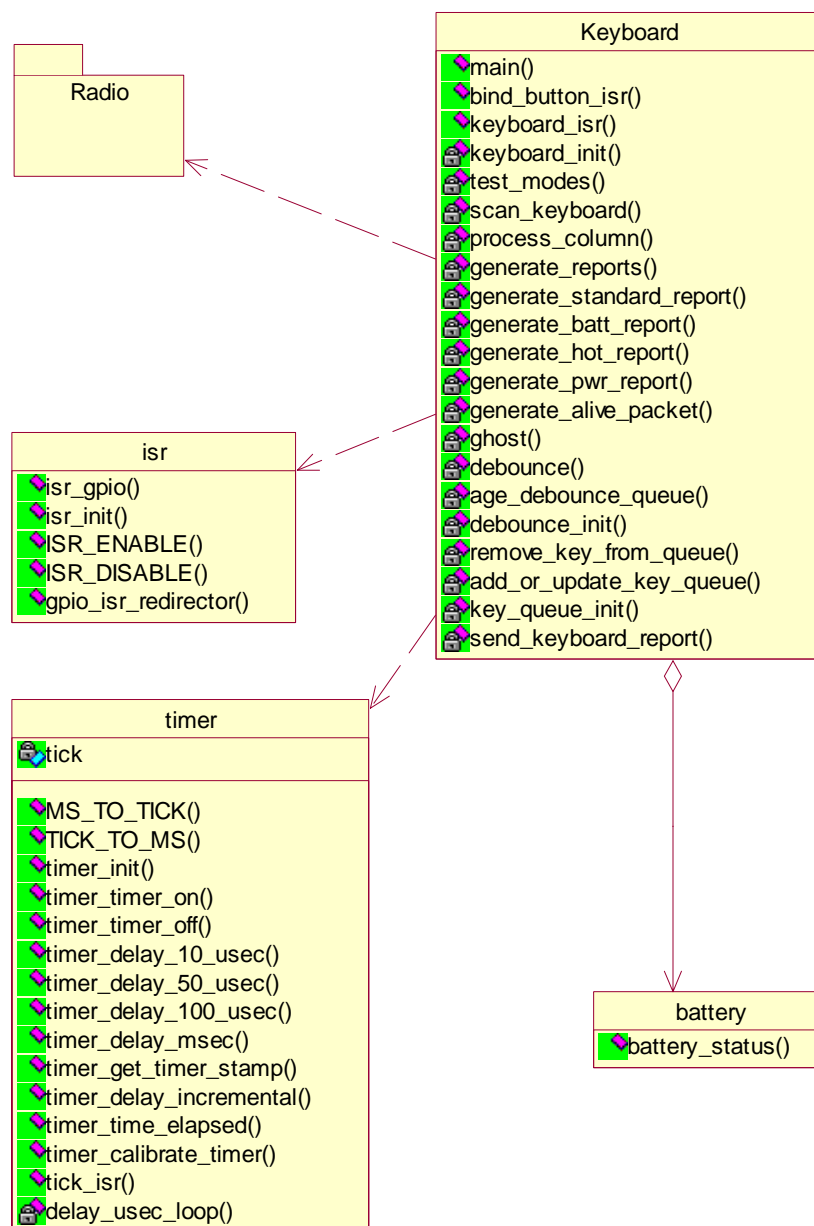


Figure 6: RDK Keyboard Architecture

## 5.2 Normal Keyboard Operation

Normal operation of the keyboard is initiated by plugging the WirelessUSB Bridge into a PC and waiting for it to enumerate. Once this is complete, insert three fresh AA batteries into the internal keyboard battery compartment (see Figure 4). In order for the keyboard to communicate with the bridge, they need to execute a “binding” process. Press the “bind” button on the WirelessUSB Bridge and the “bind” button on the keyboard, within approximately 5 seconds of each other, to initialize the “binding” process. The “bind” process can be repeated multiple times until successful. The keyboard will communicate with the Bridge and establish a connection. The keyboard is now ready for normal operation.

### 5.2.1 Ghost Key Detection

Ghost keys are possible on the RDK keyboard because it does not utilize diodes with the keyboard switches. Ghost keys are caused when three keys are pressed at the same time and two of the keys are on the same column and two of the keys are on the same row. When scanning the keyboard, it appears that four keys have been pressed and it is impossible to tell which three of the four keys are actually valid. The keyboard code detects this condition and does not send a report until one of the three keys is released.

For example, assume the keys (RowX,ColumnA), (RowX,ColumnB), and (RowY,ColumnA) have been pressed as shown in Figure 7. It appears that the key (RowY,ColumnB) has been pressed as well when it has not since the other keys electrically connect RowY to ColumnB.

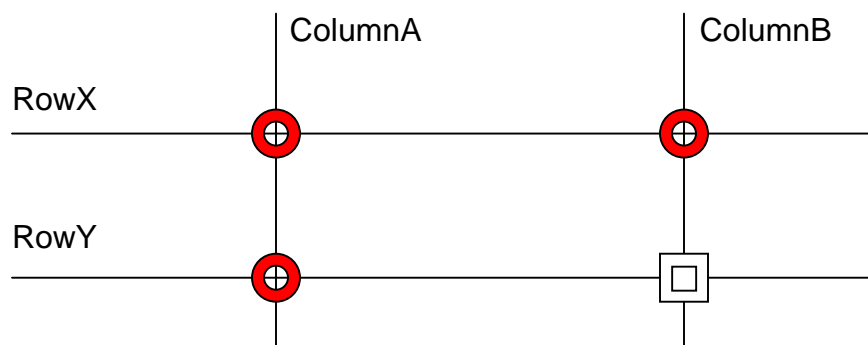


Figure 7: Ghost Key Example

### 5.3 Platform & Architecture Portability

The keyboard firmware was designed to be easily ported from one hardware platform to another platform with a simple re-mapping of pins on the PSoC. The file *pd9174.h* maintains the pin mapping definitions that are used throughout the code and is included in about every file by using the macro *PLATFORM\_H* that is defined in *appconfig.h*.

The keyboard scan matrix is defined in *kdefs.h* and may need to be changed for different keyboards.

Porting the code to another microprocessor architecture requires modification or leverage of the existing code for processor specific features, along with pin definitions.

### 5.4 Initialization

Initialization of the PSoC chip is done by code that is generated in *boot.asm* by the PSoC designer software. The module *boot.asm* calls main once the PSoC has been configured and initialized.

Main initializes the components of the keyboard along with timer, isr and radio modules. The main routine then goes into an infinite loop monitoring keyboard activity and sleeping between keystrokes.

### 5.5 Configuration Options

All configuration options for the application can be found in the *appconfig.h* file. There are other configuration options, pertaining to the radio subsystem, which can be found in the *ls\_config.h* file. A description of these options can be found in the CY4632 Protocol Library document.

#### 5.5.1 KEYBOARD\_KEEP\_ALIVE\_TIMEOUT

This configuration value sets the period at which the firmware will generate a “KEEP\_ALIVE” packet since the last keyboard report when a key is held down. The default is 100 milliseconds.

#### 5.5.2 KEY\_DOWN\_DELAY\_SAMPLE\_PERIOD

This configuration value sets the period at which the firmware polls the hardware for keyboard events to transmit over the radio. This



poll period is only active when the keyboard has not entered sleep because key(s) are currently being pressed. The default value is 10 milliseconds.

#### 5.5.3 KEYBOARD\_DEBOUNCE\_COUNT

The button debounce logic detects changes in button state and immediately indicates a change causing a report to be sent to the radio. The debounce logic then blocks out any further button state changes for the specified debounce time. This operation is somewhat different from the usual method of waiting for a button to stabilize, during a debounce time, and then reporting the change in button state. It is implemented this way to improve button-reporting latency.

This configuration value sets the debounce time for buttons that are pressed. It is measured in units of the poll rate. For example, if KEYBOARD\_DEBOUNCE\_COUNT is defined as 2 and KEY\_DOWN\_DELAY\_SAMPLE\_PERIOD is defined as 10, then the button debounce time will be 20 milliseconds. The default setting is 2.

#### 5.5.4 KEYBOARD\_MULTIMEDIA\_SUPPORT

This configuration definition is used to selectively compile support for multimedia (hot) keys. If this value is defined, then multimedia key support is compiled into the executable image. If it is not defined, then the multimedia support code is omitted.

#### 5.5.5 MFG\_TEST\_CODE

This configuration definition is used to selectively compile in the manufacturing test code.

#### 5.5.6 MFG\_ENTER\_BY\_KEY\_NOT\_PIN

This configuration definition is used to select whether the manufacturing test code is executed by pulling a PSoC pin to ground or by the test mode module. When this value is defined, then the manufacturing test code may be executed by holding the system sleep key and the bind button when the batteries are inserted into the keyboard. If it is not defined, then the manufacturing test code may be executed by pulling a defined port pin to ground within 100 milliseconds of power on. See section 6.3.1 for the port pin definition.

#### 5.5.7 KEYBOARD\_TEST\_MODES

This configuration definition is used to selectively compile code for keyboard test modes. If this value is defined, then test modes are compiled into the executable image. If it is not defined, then the test mode code is omitted. The test modes are described in section 5.8.

#### 5.5.8 KEYBOARD\_TEST\_MODE\_PERIOD

This configuration value sets the period that the keyboard generates the test key presses. A key press consists of a scan code as the down key and a NULL as the up key. The default value is 100 ms.

#### 5.5.9 PANGRAM\_TEST\_MODE

This configuration definition is used to selectively compile in the pangram test mode. A pangram is a sentence that contains all of the letters of the alphabet at least once.

#### 5.5.10 KEYBOARD\_BATTERY\_VOLTAGE\_SUPPORT

This configuration definition is used to selectively compile support for battery voltage level reporting. If this value is defined, then battery voltage level reporting is compiled into the executable image. If it is not defined, then the battery voltage level reporting code is omitted.

#### 5.5.11 CBK\_500\_KEYBOARD\_MATRIX

This configuration definition is used to selectively compile in the keyboard matrix for the beta and final RDK keyboard hardware.

#### 5.5.12 KEYBOARD\_FAST\_SCAN

This configuration definition is used to selectively compile in the Cypress Semiconductor fast scan algorithm.

#### 5.5.13 KEYBOARD\_TX\_TIMEOUT

This configuration value sets the maximum time that the keyboard will try to send a report to the bridge.

#### 5.5.14      TIMER\_CAL

This configuration definition is used to selectively compile in the one-millisecond timer calibration routine. The routine is called on power on and during protocol reconnect.

#### 5.5.15      ENCRYPT\_DATA

This configuration definition is used to selectively compile in data encryption for the keyboard. Please contact Cypress Applications support for the encryption source code.

#### 5.5.16      MOUSE\_EMULATION\_MODE

This configuration definition is used to selectively compile in the Mouse Emulation Mode. The Scroll Lock key is used to toggle this mode on/off. Once in this mode the arrow keys are used to move the mouse. The Delete key is the left mouse button, the End key is the right mouse button, and Page Up and Page Down emulate the scroll wheel.

#### 5.5.17      KEYBOARD\_POWER\_ON\_BIND

This configuration definition is used to selectively compile in the option to enter bind mode on power-up when the device has not been previously bound to a bridge.

#### 5.5.18      PLATFORM\_H

This configuration value identifies the header file that has the platform configuration information. The default value is *pd9174.h*, which is identifier for the keyboard board that is shipped with the RDK. It is anticipated that this macro will change when the code is ported to another platform.

### 5.6          Radio Subsystem

The radio subsystem is composed of the following modules and provides an API to the application for sending data over the radio.

- bind
- protocol
- radio
- spi
- nvram

Please refer to the WirelessUSB Theory of Operation and CY4632 Protocol Library documentation for theory of operation along with a detailed description of the API and configuration options. The *spi* module is coupled to the platform in order to communicate with the radio.

## 5.7 Keyboard Wireless Protocol

The keyboard protocol has been optimized to reduce the “on-time” of the radio and power consumption.

The radio library offers the ability to send variable length packets, allowing the opportunity to minimize the number of bytes transmitted over the air, in order to extend battery life.

The following transmission packet formats are implemented in this RDK. The report formats show the application payload and the radio protocol overhead with example packet headers and CRC bytes.

### 5.7.1 Keyboard Application Report Formats

There are five possible keyboard application reports. The reports are:

- Standard 101 Keys Report
- Multimedia Keys Report
- Power Keys Report
- Keep Alive Report
- Battery Voltage Level Report

The reports are distinguished by the first application report byte to reduce the number of bytes required in the most common report (Standard 101 Keys Report). The first application report byte is Scan Code 1 if the byte is less than 0xFC. Otherwise, the first application report byte is the Report Type (Multimedia, Power, Battery, or Keep Alive). This also assumes that multimedia and power keys do not utilize modifier keys and that 0xFF, 0xFE, 0xFD and 0xFC are not valid Standard 101 key scan codes.

Packet Headers starting with 0x7X require special handling when Null Packet Support is enabled. A Packet Header of 0x70 is a “NULL” packet and indicates that all the data bytes are zero for the

Standard 101 Keys Report. A Packet Header of 0x79 is a Keep Alive packet.

Trailing zeros in the reports are also removed to further minimize the number of bytes sent by the radio.

The LS radio sends the reports with the format shown in Table 2.

**Table 2: LS Generic Report**

Packet Header	Application Report	Checksum
---------------	--------------------	----------

Note: The Packet Headers and Checksums utilized in this document are for example purposes only and may change as required by the protocol.

#### 5.7.1.1 Standard 101 Keys Report

A “Scan Code 1” byte not equal to 0xFF, 0xFE, 0xFD and 0xFC indicates that this report is a Standard 101 Keys Report. The Standard 101 Keys report is formatted to optimize the assumption that the most common report will have only one non-zero scan code without a modifier. The full Standard 101 Keys report format is shown in Table 3.

**Table 3: Standard 101 Keys Report Format**

Byte	Name
1	Scan Code 1 ( $< 0xFC$ )
2	Modifier Keys
3	Scan Code 2
4	Scan Code 3
5	Scan Code 4
6	Scan Code 5
7	Scan Code 6

Example: The following reports would be sent if a user presses an “a” on the keyboard. The down key packet sent from the keyboard to the bridge is shown in Table 4.

**Table 4: Example "a" down key Standard 101 Keys Report**

Packet Header	Application Report	Checksum
0x40	Scan Code 1	0x44
	0x04	

The bridge would add the trailing zeros, insert the reserved byte, rearrange the modifier and scan code 1 bytes and remove the packet header and checksum to produce the USB report shown in Table 5.

**Table 5: Example USB report for the "a" down key**

Modifier keys	Reserved	Scan Code 1	Scan Code 2	Scan Code 3	Scan Code 4	Scan Code 5	Scan Code 6
0x00	0x00	0x04	0x00	0x00	0x00	0x00	0x00

The up key packet sent from the keyboard to the bridge (all data bytes are zero) is shown in Table 6 with Null Packet Support enabled and in Table 7 with Null Packet Support disabled.

**Table 6: Standard 101 Key Null Packet Report (Null Packet Support enabled)**

Packet Header
0x70

**Table 7: Example up key Standard 101 Keys Report (Null Packet Support disabled)**

Packet Header	Application Report	Checksum
0x40	Scan Code 1	0x40
	0x00	

The bridge would add the trailing zeros, insert the reserved byte, and remove the packet header to produce the USB report shown in Table 8.

**Table 8: Example USB report for a Standard 101 Key Null Packet Report**

Modifier keys	Reserved	Scan Code 1	Scan Code 2	Scan Code 3	Scan Code 4	Scan Code 5	Scan Code 6
0x00	0x00	0x00	0x00	0x00	0x00	0x00	0x00



### 5.7.1.2 Multimedia Keys (Hot keys) Report

A “Report Type” byte of 0xFF indicates that this report is a Multimedia Keys Report. The Multimedia Keys report format is shown in Table 9.

**Table 9: Multimedia Keys Report Format**

Byte	Name
1	Report Type (0xFF)
2	Hot Key Scan Code (upper 8 bits)
3	Hot Key Scan Code (lower 8 bits)

Example: The following reports would be sent if a user presses “Volume Increase” (Hot Key 8) key on the keyboard.

The “Volume Increase” down key packet sent from the keyboard to the bridge is shown in Table 10.

**Table 10: Example “Volume Increase” down key Multimedia Keys Report**

Packet Header	Application Report			Checksum
0x41	Report Type	Hot Key Scan Code (upper 8 bits)	Hot Key Scan Code (lower 8 bits)	0x29
	0xFF	0x00	0xE9	

The up key packet sent from the keyboard to the bridge is shown in Table 11.

**Table 11: Example up key Multimedia Keys Report**

Packet Header	Application Report	Checksum
0x45	Report Type	0x44
	0xFF	

### 5.7.1.3 Power Keys (Suspend/Sleep) Report

A “Report Type” byte of 0xFE indicates that this report is a Power Keys Report. The Power Keys report format is shown in Table 12.

**Table 12: Power Keys Report Format**

Byte	Name
1	Report Type (0xFE)
2	Power Key Scan Code

Example: The following reports would be sent if a user presses the “Suspend/Sleep” (Power Key 0) key on the keyboard.

The “Suspend/Sleep” down key packet sent from the keyboard to the bridge is shown in Table 13.

**Table 13: Example "Suspend/Sleep" down key Power Keys Report**

Packet Header	Application Report		Checksum
0x41	Report Type	Power Key Scan	0xC1
	0xFE	0x82	

The up key packet sent from the keyboard to the bridge is shown in Table 14.

**Table 14: Example up key Power Keys Report**

Packet Header	Application Report	Checksum
0x45	Report Type	0x43
	0xFE	

#### 5.7.1.4 Keep Alive Report

A “Report Type” byte of 0xFC indicates that this report is a Keep Alive Report. When Null Packet Support is enabled, a “Packet Header” byte of 0x79 also indicates that this report is a Keep Alive Report.

Example of a Keep Alive reports sent from the keyboard to the bridge are shown in Table 15 with Null Packet Support enabled and Table 16 with Null Packet Support disabled.

**Table 15: Keep Alive Report (Null Packet Support enabled)**

Packet Header
0x79

**Table 16: Example Keep Alive Report (Null Packet Support disabled)**

Packet Header	Application Report	Checksum
0x45	Report Type	0x41
	0xFC	

If the bridge does not receive a Keep Alive packet or an up key within a specified interval (KEYBOARD\_KEEP\_ALIVE\_TIMEOUT) while a down key is present, the bridge will generate an up key to the computer.

#### 5.7.1.5 Battery Voltage Level Report

A "Report Type" byte of 0xFD indicates that this report is a Battery Voltage Level Report. The Battery Voltage Level report format is shown in Table 17.

**Table 17: Battery Voltage Level Report Format**

Byte	Name
1	Report Type (0xFD)
2	Battery Voltage Level

The Battery Voltage Level ranges from 1 (low) to 10 (full).

The Battery Voltage Level Report can be sent at any time. However, it is anticipated that the report will be sent approximately every 10K - 16K reports.

Example of a Battery Voltage Level Report with fully charged batteries is shown in Table 18.

**Table 18: Example "full" Battery Voltage Level Report**

Packet Header	Application Report		Checksum
0x41	Report Type	Battery Voltage Level	0x48
	0xFD	0x0A	

Example of a Battery Voltage Level Report with low batteries is shown in Table 19.

**Table 19: Example "low" Battery Voltage Level Report**

Packet Header	Application Report		Checksum
0x41	Report Type	Battery Voltage Level	0x3F
	0xFD	0x01	

## 5.8 Test Modes

This RDK provides a compile-time option of adding test modes to the keyboard; see Section 5.5.7 for enabling this option. The test mode module is implemented in a way that it can be easily extended to add other test modes. Currently there are only two test modes supported in the module. When this option is not enabled then all test mode code is removed from the compilation.

The first test mode is initiated by holding down the left ctrl, left alt, right alt, right ctrl, and F1 keys at the same time. If PANGRAM\_TEST\_MODE is defined, the test sends the key up/down scan codes for the test pangram: *"a quick brown fox jumps over the lazy dog.<carriage return>"*. Otherwise the up/down scan codes are repeatedly sent for the test sequence "wirelessusb" followed by the same number of backspaces. The test repeats the appropriate sequence until the escape key is pressed. Once the test has finished execution, the keyboard will return to normal operation.

The repeating "x" test selection is initiated by holding down the left ctrl, left alt, right alt, right ctrl, and F3 keys at the same time. The test continuously sends the "x" key up/down scan codes. The test continues until the escape key is pressed. Once the test has finished execution, the keyboard will return to normal operation.

## 5.9 Manufacturing Test Mode

The RDK provides a compile-time option of adding a manufacturing test mode to the keyboard; see Section 5.5.5 for enabling this option.

If MFG\_TEST\_CODE and ENTER\_BY\_KEY\_NOT\_PIN are defined, holding down the system sleep key and the bind button while inserting the batteries into the keyboard will enter the manufacturing test mode. The only way to exit this test mode is to cycle power.

#### 5.10 Flash Security

The keyboard project within PSoC Designer has a file called *FlashSecurity.txt*. This file specifies access rules to blocks of the Flash ROM. Please see the documentation at the top of the file for definitions. This file is shipped with its default configuration in the RDK with the exception of one change. The block starting at address 3E80 hex has been changed from **W**: Full (Write protected) to **U**: Unprotected. This location of Flash has been dedicated to saving non-volatile configuration values for the radio subsystem.

#### 5.11 Battery Monitor

The battery monitor circuit is implemented using an RC circuit connected to two PSoC pins. The firmware has been tuned to provide a ten level measurement of the battery voltage. This is a process that is time intensive. Following is an explanation of the process to measure the battery voltage.

The process starts by first setting the PSoC pins BATT\_LEV1 and BATT\_LEV2 to high impedance inputs and allowing the RC circuit to reach a steady state. This allows BATT\_LEV1 to reach the same potential as the battery with the capacitor. BATT\_LEV2 is then driven to ground and the RC time constant is measured to the point at which the BATT\_LEV1 detects a logic 0 state. This time measurement is the battery voltage measurement. Next, both BATT\_LEV1 and BATT\_LEV2 are driven to a logic 1 state initializing the RC circuit for a VCC measurement. BATT\_LEV1 is set to a high impedance input and BATT\_LEV2 is driven to ground. Once again the RC time constant is measured to the point at which the BATT\_LEV1 detects a logic 0 state. This time becomes a VCC reference measurement.

The firmware then uses the battery measurement and VCC measurement to compute a battery level between 1 and 10 inclusive. Battery status reports should have a minimum of one second between requests to allow the RC circuit to reach a steady state.

## 6. KEYBOARD CODE MODULES

Following are descriptions of the module contents. For concept of operation, see section 5.

### 6.1 KEYBOARD

The keyboard module contains the main entry point, test modes, a routine for scanning the keyboard as well as management of report frequency to the Bridge.

#### 6.1.1 Defines & Types

**Table 20: Keyboard Module Defines & Types**

Define/Type	Description
APP_TX_PACKET	This union structure defines the data payload portion of the radio transmit packet.
HID_APP	This structure defines all of the HID related variables.

**Table 21: HID\_APP Structure Definitions**

Element	Description
key_queue	A KEY structure array of KEY_QUEUE_LEN elements. Used to store pressed key index values.
status	A STATUS_STATE structure used to maintain the current status of the keyboard.
debounce	A DEBOUNCE_ENTRY structure array of DEBOUNCE_QUEUE_LENGTH elements. Used to debounce pressed key index values.
prior_key_state	An UINT8 array of COLUMNS elements. Used to store the previous state of keyboard matrix.

#### 6.1.2 Variable Definitions

**Table 22: Keyboard Module Variable Definitions**

Variable	Description
hid	A HID_APP structure containing the HID related variables.
report_packet	This is a pointer to an APP_TX_PACKET structure.
ts	A TIME_STAMP structure used for timing.



last_transfer_ts	A TIME_STAMP structure used for timing to generate KEEP_ALIVE packets.
test_mode	A variable used to store the current test mode state if KEYBOARD_TEST_MODES is defined.
sentence_table_index	A variable used to store the current position in the test sequence if KEYBOARD_TEST_MODES is defined.
mouse_emulation	A variable used to store the current state of the MOUSE_EMULATION_MODE.

### 6.1.3 Functions

**Table 23: Keyboard Module Functions**

Function	Linkage	Description
main	external	This function is the main entry point for the application. It initializes all keyboard application components and radio components and executes the poll loop. Radio transmission takes place when there are keyboard events to send.
bind_button_isr	external	This function is called from interrupt context when the bind button is pressed.
keyboard_isr	external	This function is called from interrupt context when a key is pressed.
keyboard_init	static	This function initializes all components of the keyboard application.
test_modes	static	This function adds the appropriate test key index to the key queue if a test mode is active.
scan_keyboard	static	This function scans the keyboard matrix and stores the results in the array hid.key_state[].
process_column	static	This function compares the arrays hid.key_state[] to hid.prior_key_state[] for the specified column.

generate_reports	static	This function calls the other generate functions if the GENERATE_REPORT status bit is set.
generate_standard_report	static	This function generates the Standard 101 Keys report.
generate_batt_report	static	This function generates the Battery Voltage Level report.
generate_hot_report	static	This function generates the Multimedia (Hot) Keys report.
generate_pwr_report	static	This function generates the Power Keys report.
generate_alive_packet	static	This function generates the Alive Packet report.
ghost	static	This function determines if a ghost key condition exists.
debounce	static	This function starts the debounce clock when a button is pressed and blocks out further button changes until the debounce time has expired.
age_debounce_queue	static	This function decrements debounce values for all keys every time the keyboard buttons are polled. This provides a debounce period for when a button is pressed
debounce_init	static	This function initializes the debounce logic for the buttons.
remove_key_from_queue	static	This function removes the specified key index from the hid.key_queue[] array.
add_or_update_key_queue	static	This function adds the specified key index to the hid.key_queue[] array.
key_queue_init	static	This function initializes the hid.key_queue[] array.
send_keyboard_report	static	This function attempt to send the keyboard report to the bridge.

## 6.2 BATTERY

This module measures the battery voltage level and computes a level from 1 to 10. Time for the RC circuit to stabilize with the battery voltage needs to be given before calling this module. An application should guarantee that a minimum time of one second between successive battery status requests.

### 6.2.1 Functions

**Table 24: Battery Module Functions**

Function	Linkage	Description
battery_status	external	This function reads a time constant related to the battery voltage and VCC (for reference) and computes a battery level from 1 to 10. See section 5.11 for details of operation.

## 6.3 MFGTEST

This module may be conditionally compiled in to provide manufacturing test support. The module configures the radio for reception and then enters a loop waiting for packets to be sent from the tester. It computes the total number of bits received and the number of invalid bits received. It then sends packets to the tester followed by the previously computed results. After which it re-enters the reception loop waiting for another test cycle. The manufacturing test code may be entered by grounding a microprocessor port pin or by the test mode mechanism defined in section 5.8. The method of entry is a compile time option described in section 5.5.6. The manufacturing test code can only be exited by cycling power.

### 6.3.1 Defines & Types

**Table 25: MFGTest Module Defines & Types**

Define/Type	Description
MFG_PN_CODE	This macro defines the PN code used for the manufacturing test. See radio documentation.
MFG_CHANNEL	This macro defines the channel used for the manufacturing test. See radio documentation.

MFG_THRESHOLD_L	This macro defines the threshold when correlating a '0' data bit. See the radio documentation.
MFG_THRESHOLD_H	This macro defines the threshold when correlating a '1' data bit. See the radio documentation.
MFG_PA_BIAS	This macro defines the power amplifier bias used for the test. See radio documentation.
MFG_EOF_TIMEOUT	This macro defines the number of bits that need to be seen before end-of-frame is detected. See radio documentation.
MFG_RX_TIMEOUT	The number of milliseconds between two packets, once packet sending has started, before the receiving loop will timeout.
MFG_NUM_PACKETS	The number of packet expected to receive and send.
MFG_PACKET_PAYLOAD_SIZE	The data size of the packets being received and sent. Does not include header and checksum overhead.
MFG_PRE_TX_DELAY	The time in milliseconds to wait after receiving and before sending out data packets.
MFG_INTER_TX_DELAY	The time in milliseconds to wait in between data packets being sent out.
MFG_NUM_RESULTS_PACKETS	The number of times to send each result packet.
MFG_PRE_RESULTS_DELAY	The time in milliseconds to wait before sending out the results packets.
MFG_INTER_RESULTS_DELAY	The time in milliseconds in between each repetition of result packet sent.
MFG_TEST_PORT	The port owning the pin used to enter manufacturing test mode.
MFG_TEST_PIN	The pin used to enter manufacturing test mode. This is used in conjunction with MFG_TEST_PORT.

MFG_TEST_DM0	Drive mode register 0 for the port used in MFG_TEST_PORT. This is used to change drive characteristics during power-up.
MFG_TEST_DM1	Drive mode register 1 for the port used in MFG_TEST_PORT. This is used to change drive characteristics during power-up.
MFG_HDR_TEST	Header byte for test data packets sent to the tester from the device.
MFG_HDR_RES1	Header byte for results packet number one.
MFG_HDR_RES2	Header byte for results packet number two.
MFG_HDR_RES3	Header byte for results packet number three.
MFG_TEST_PKT_SIZE	Total packet size defined as MFG_PACKET_PAYLOAD_SIZE + header byte + checksum byte.
MFG_RES_PKT_SIZE	Packet size for results packets. This is hard coded to 10 bytes and includes header byte and checksum byte.

### 6.3.2 Functions

**Table 26: MFGTest Module Functions**

Function	Linkage	Description
mfg_pin_check	external	This function checks the state of the defined manufacturing port pin. If the port pin is low, then the manufacturing test is executed.
mfg_test	external	This is the top-level function for the manufacturing test.
mfg_setup_radio	static	This function initializes the radio to a manufacturing test state.
mfg_receive_test_packets	static	This function receives test packets sent from the tester to the device.
mfg_send_test_packets	static	This function sends test packets from the device to the tester.

mfg_send_results	static	This function sends statistics of data that was received by the device.
mfg_send_result_packet	static	This function performs the actual sending of the results packet with appropriate delays.

#### 6.4 PDC9174

This module is used to implement platform specific code. Currently the *pdc9174.c* file is empty. The *pdc9174.h* file contains the entire platform specific defines for pin and port assignments for a specific feature. Porting from one platform to another should only require modifications to these two files assuming no other features are added or removed.

#### 6.5 PSOCGPIOINT

This module is an assembly file and is generated automatically by the PSoC Designer in the lib directory. It is mentioned here because it needs to be modified after PSoC Designer has generated the code. PSoC Designer generates code such that when a GPIO interrupt occurs the vector jumps to this module. This module in turn needs to jump to the *isr\_gpio* interrupt service routine provided in the ISR module, see section 6.6. If GPIO interrupts stop working, then this is a good place to check since this is a generated file.

#### 6.6 ISR

The purpose of this module is to handle GPIO interrupt handling. It provides a single entry point for all GPIO interrupts and calls functions based upon which interrupt is enabled. The PSoC does not provide the ability to determine which GPIO generated the interrupt.



## 6.6.1 Functions

**Table 27: ISR Module Functions**

Function	Linkage	Description
isr_gpio	external	This is the main GPIO interrupt service routine. It calls interrupt handlers if the interrupt is enabled using the <i>gpio_isr_redirector()</i> function. The interrupt handlers need to be callable even if they are not the source of the interrupt.
isr_init	external	This function initializes the interrupt enable registers and turns on interrupts for the microprocessor.
ISR_ENABLE	external	This macro function enables an interrupt handler at its associated port pin.
ISR_DISABLE	external	This macro function disables an interrupt handler at its associated port pin.
gpio_isr_redirector	external	This function is used as a mechanism to bypass the compiler's inefficient ISR mechanism of pushing all registers when an ISR makes another function call

## 6.7 TIMER

The timer module provides a one-millisecond tick for the system. The tick resolution can be changed, but is set for one millisecond for the keyboard. This module requires the use of a timer block on the PSoC. The delay function used for millisecond timing will provide at least the delay requested with no more than one additional millisecond of delay. The microsecond delay functions have been tuned as best as possible for a 12 MHz clock setting for the microprocessor. The millisecond delay function will sleep the PSoC for the duration of the requested delay. The microprocessor wakes just long enough to update the tick every millisecond and check if the delay has been met and then returns to sleep mode if it

has not. See documentation in the module for requirements on configuring the PSoC block.

### 6.7.1 Defines & Types

**Table 28: Timer Module Defines & Types**

Define/Type	Description
TIME_STAMP	This defines the type of the time stamp.
MS_TO_TICK	This macro is used to convert milliseconds to ticks.
TICK_TO_MS	This macro is used to convert ticks to milliseconds.
timer_delay_1_usec	This macro is used to delay for 1 microsecond with a microprocessor clock of 12MHz.

### 6.7.2 Variable Definitions

**Table 29: Timer Module Variable Definitions**

Variable	Description
tick	This variable keeps track of the number of ticks since the timer was turned on.

### 6.7.3 Functions

**Table 30: Timer Module Functions**

Function	Linkage	Description
tick_isr	external	This function is the interrupt service routine for the timer expired interrupt. It increments the tick counter.
timer_init	external	This function initializes the tick counter and starts the timer.
timer_timer_on	external	This function turns the timer and system tick on.
timer_timer_off	external	This function turns the timer and system tick off.
timer_delay_10_usec	external	This function delays for 10 microseconds.
timer_delay_50_usec	external	This function delays for 50 microseconds.
timer_delay_100_usec	external	This function delays for 100 microseconds.

timer_delay_msec	external	This function delays for the number of requested milliseconds plus up to one additional millisecond.
timer_get_time_stamp	external	This function returns the current tick counter value.
timer_delay_incremental	external	This function takes a time stamp and delays for the incremental time between the time stamp and the requested period. This function is used for meeting poll rate requirements.
timer_time_elapsed	external	This function returns true if the specified amount of time has elapsed since a given time stamp.
timer_calibrate_timer	external	This function calibrates the one-millisecond timer by using the System Clock as a reference.

## 6.8 TICKINT

This module is an assembly file and is generated automatically by the PSoC Designer in the lib directory. It is mentioned here because it needs to be modified after PSoC Designer has generated the code. PSoC Designer generates code such that when a Timer interrupt occurs the vector jumps to this module. This module in turn needs to jump to the *tick\_isr* interrupt service routine discussed in section 6.7.

## **7. REFERENCES**

CY3632 Wireless USB Development Kit documents

WirelessUSB Theory of Operation

CY4632 Protocol Library

PSoC Designer version 4.1 documentation

CY4632 RDK Kit schematics

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