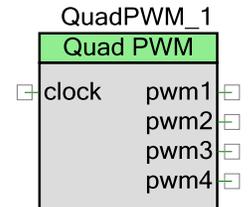


# Quad PWM

## v1.0

## Features

- Generates 4x 8-bit PWM outputs from a single UDB
- Easy APIs to initialize and set duty cycles
- Perfect for Low-end PSoC 4 devices



## General Description

The Quad PWM component provides four 8-bit PWM outputs using a single Universal Digital Block (UDB). The current PWM component available in PSoC Creator only provides 2 PWM output signals per UDB.

All four PWM signals share the same period, which depends on the input clock frequency. The duty cycles are set directly in the customizer or by the `SetDutyCycle()` API.

## When to Use this Component

The Quad PWM component is recommended on low-end PSoC 4 devices that do not have many UDB resources; or designs that lack of hardware resources and require many PWM signals.

## Input/Output Connections

This section describes the various input and output connections for the Quad PWM component.

**Note** All signals are active high unless otherwise specified.

| Input | May Be Hidden | Description                                       |
|-------|---------------|---|
| clock | N             | The clock input defines the PWM output frequency. |

| Output | May Be Hidden | Description  |
|--------|---------------|--|
| pwm1   | N             | The pwm1 is the first pulse-width modulated output. Its duty cycle is set in the customizer <code>DutyCycle1</code> parameter or by <code>SetDutyCycle()</code> .  |
| pwm2   | N             | The pwm2 is the second pulse-width modulated output. Its duty cycle is set in the customizer <code>DutyCycle2</code> parameter or by <code>SetDutyCycle()</code> . |
| pwm3   | N             | The pwm3 is the third pulse-width modulated output. Its duty cycle is set in the customizer <code>DutyCycle3</code> parameter or by <code>SetDutyCycle()</code> .  |

| Output | May Be Hidden | Description   |
|--------|---------------|---|
| pwm4   | N             | The pwm4 is the forth pulse-width modulated output. Its duty cycle is set in the customizer DutyCycle4 parameter or by SetDutyCyle(). |

## Component Parameters

Drag a PWM component onto your design and double click it to open the **Configure** dialog.

### DutyCycleX

Define the duty cycle of pwmX output. The value range is from 0 (0% duty cycle) to 255 (100% duty cycle).

## Clock Selection

There is no internal clock in this component. You must attach a clock source. The PWM frequency equation is calculated as:

$$\text{PWM Freq (Hz)} = \text{Clock Freq (Hz)} / 1024$$

## Application Programming Interface

Application Programming Interface (API) routines allow you to configure the component using software. The following table lists and describes the interface to each function. The subsequent sections cover each function in more detail.

By default, PSoC Creator assigns the instance name "QuadPWM\_1" to the first instance of a component in a given design. You can rename it to any unique value that follows the syntactic rules for identifiers. The instance name becomes the prefix of every global function name, variable, and constant symbol. For readability, the instance name used in the following table is "QuadPWM".

### Functions

| Function               | Description  |
|------------------------|--|
| QuadPWM_Init()         | Initializes the PWM based on the duty cycles provided in the customizer. |
| QuadPWM_SetDutyCycle() | Set the duty cycle for the given PWM output.                             |

**void QuadPWM\_Init(void)**

**Description:** Initializes the PWM based on the duty cycles provided in the customizer.

**Parameters:** None

**Return Value:** None

**Side Effects:** None

**void QuadPWM\_SetDutyCycle(uint32 pwm, uint32 dutyCycle)**

**Description:** Set the duty cycle for the given PWM output

**Parameters:** pwm: PWM output to be set (from 1 to 4)  
dutyCycle: new duty cycle value (from 0 to 255)

**Return Value:** None

**Side Effects:** None

**API Constants**

| Function               | Description                           |
|------------------------|---------------------------------------|
| QuadPWM_MAX_DUTY_CYCLE | Maximum duty cycle supported          |
| QuadPWM_MIN_DUTY_CYCLE | Minimum duty cycle supported          |
| QuadPWM_PWM_1          | Index to PWM 1 output                 |
| QuadPWM_PWM_2          | Index to PWM 2 output                 |
| QuadPWM_PWM_3          | Index to PWM 3 output                 |
| QuadPWM_PWM_4          | Index to PWM 4 output                 |
| QuadPWM_DP_INIT        | Initialization value for the datapath |

**Sample Firmware Source Code**

This section shows an example of the main loop using this component.

```

#include <project.h>

int main()
{
    uint8 counter = 0;

    QuadPWM_Init();

    for(;;)
    {
        counter++;
        QuadPWM_SetDutyCycle(QuadPWM_PWM_1, counter);
        CyDelay(1000);
    }
}

```

## Resources

The UDB Implementation utilizes the following resources.

| Configuration | Resource Type  |            |              |               |              |            |
|---------------|----------------|------------|--------------|---------------|--------------|------------|
|               | Datapath Cells | Macrocells | Status Cells | Control Cells | DMA Channels | Interrupts |
| 4x 8-bit PWM  | 1              | 6          | 0            | 0             | –            | –          |

## DC and AC Electrical Characteristics

The following values indicate expected performance and are based on initial characterization data.

### SRAM Scrubber DC Specifications

| Parameter | Description | Conditions | Min | Typ | Max | Units |
|-----------|-------------|------------|-----|-----|-----|-------|
|           | TBD         |            |     |     |     |       |

### SRAM Scrubber AC Specifications

| Parameter | Description           | Conditions | Min | Typ | Max    | Units |
|-----------|-----------------------|------------|-----|-----|--------|-------|
| PWMFreq   | Maximum PWM frequency |            |     |     | 46.875 | KHz   |

## Component Changes

This section lists the major changes in the component from the previous version.

| Version | Description of Changes | Reason for Changes / Impact |
|---------|------------------------|-----------------------------|
| **      | Initial release        | Initial release             |